

Course Unit	Mechatronics			Field of study	Automation		
Master in	Electrical and Computers Engineering			School	School of Technology and Management		
Academic Year	2023/2024	Year of study	1	Level	2-1	ECTS credits	6.0
Туре	Semestral	Semester	1	Code	5070-792-1102-00-23		
Workload (hours)	162	Contact hours		30 PL 30 T nd problem-solving; PL - Problem-	C - S - solving, project or laboratory; TC -	E - OT Fieldwork; S - Seminar; E - Place	- O -

Name(s) of lecturer(s)

João Paulo Coelho, Ines Cristina Vinhas de Seixas

### Learning outcomes and competences

- At the end of the course unit the learner is expected to be able to: 1. Draw mechanical objects in CAD software for subsequent 3D printing; 2. Know and be able to use various types of electromechanical actuators in mechatronics applications: DC motors, brushless DC motor, stepper motors and servomotors
- 3. Implement electronic devices for motion control of various electromechanical actuators: PWM modulation and H bridge circuits;
- Know the different types of classical sensors and be able to implement electronic signal conditioning circuits.
   Use numerical calculation software for modeling and simulation of dynamic systems.
   Analyze and design PID controllers for mechatronics applications.
   Programming microcontrollers for control systems.

# Prerequisites

Before the course unit the learner is expected to be able to: 1. Linear algebra and solving differential equations 2. DC and AC circuit analysis;

- 3
- Analysis of systems in the time and frequency domain Interpret and implement circuits composed of analog or mixed electronic devices;
- 5. Microcontroller programming.

## Course contents

3D modelling using CAD tools; Signal conditioning for active and passive sensors; Electromechanical, pneumatic and hydraulic actuators; Mathematical modelling of mechatronic systems; System identification; Analysis and simulation of closed-loop control systems; Implementation of digital controllers in embedded systems.

#### Course contents (extended version)

- Modelling for prototyping using 3D printing
   Fundamental concepts of electronic circuits

   Linear elements. resistors, capacitors and inductors
   Semiconductor elements: diodes, transistors, triacs, operational amplifiers
   Fundamental laws and methods for analyzing DC and AC circuits.
- 3. Sensors and Actuators
- Sensors and signal conditioning
   Electromechanical actuators and power interfaces
- Pneumatic and hydraulic actuators
   Modeling of LIT mechatronic systems
   Methods using first principles
   Systems identification

- 5. Dynamic systems control
   Design of control systems in the continuous time domain

  - Sampling and Reconstruction
     Starred transform and s to Z mapping
     Design of control systems in the digital domain

# Recommended reading

- Robert H. Bishop. THE MECHATRONICS HANDBOOK, CRC Press, 2002
   João P. Coelho. CONTROLO DIGITAL, IPB, 2005
   João P. Coelho. SENSORES E ATUADORES, IPB, 2003
   J. Johnson e P- Picton. MECHATRONICS, Butterworth Heinrmann, 1995
   Newton C. Braga. MECHATRONICS FOR THE EVIL GENIUS, McGraw-Hill, 2006

#### Teaching and learning methods

Lectures: presentation of the course contents supported on real applications examples, problem-solving and use of simulation software. Laboratory: tutorial demonstrations of available technology to support mechatronics systems development. Development of small servomechanism applications. Non-presential hours: implementation of the practical work and final report writing.

Assessment methods

- Alternative 1 (Regular, Student Worker) (Final, Supplementary, Special)

   Projects 50% (80% related to work to be carried out outside face-to-face hours and 20% to practical class scripts)
   Final Written Exam 50%

   Alternative 2 (Student Worker) (Final, Supplementary, Special)

   Final Written Exam 100%

# Language of instruction

Portuguese

Electronic validation				
João Paulo Coelho	José Luís Sousa de Magalhaes Lima	Paulo Jorge Pinto Leitão	José Carlos Rufino Amaro	
08-10-2023	09-10-2023	26-10-2023	31-10-2023	